

# Software Meeting

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<http://www.hep.ph.qmul.ac.uk/~landon/talks>

## Overview

- Database developments
- Run control and module services

# Database Developments (1)

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## Overview

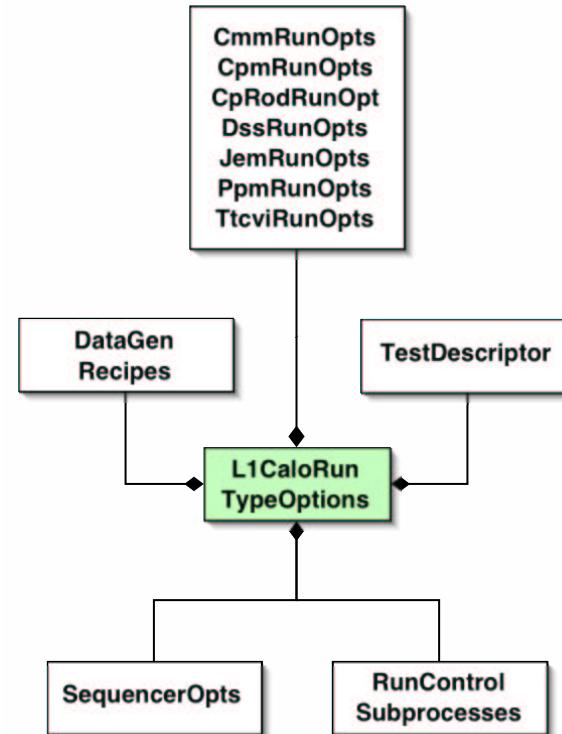
- New run type objects (see later)
- Calibration scans: calibration objects implement a new interface which accepts an object defining start point and increment
- More internal consistency: calibrations, trigger menu, IS parameters, run types, etc are now all implementations of a new interface which gets passed, Visitor style, to all DbModules

# Database Developments (2)

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## L1CaloRunTypeOptions

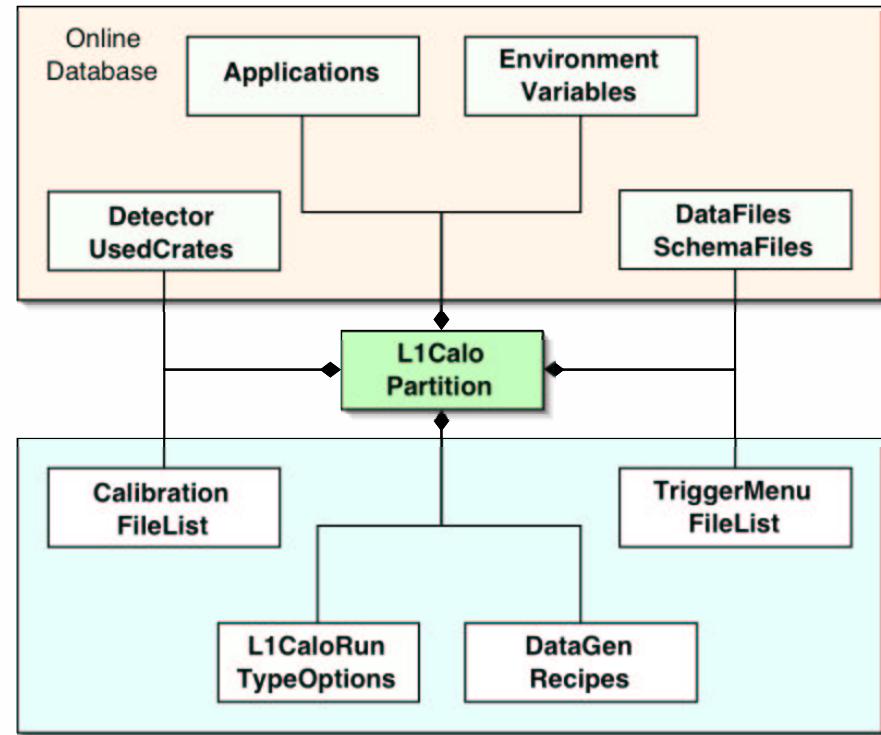
- Named object defining a run type
- Various module options (by module type or specific module)
- Options for multistep sequence runs
- TestDescriptor for this run type
- DataGenRecipes specific to this run type (NB there can also be global ones)



# Database Developments (3)

## L1CaloPartition

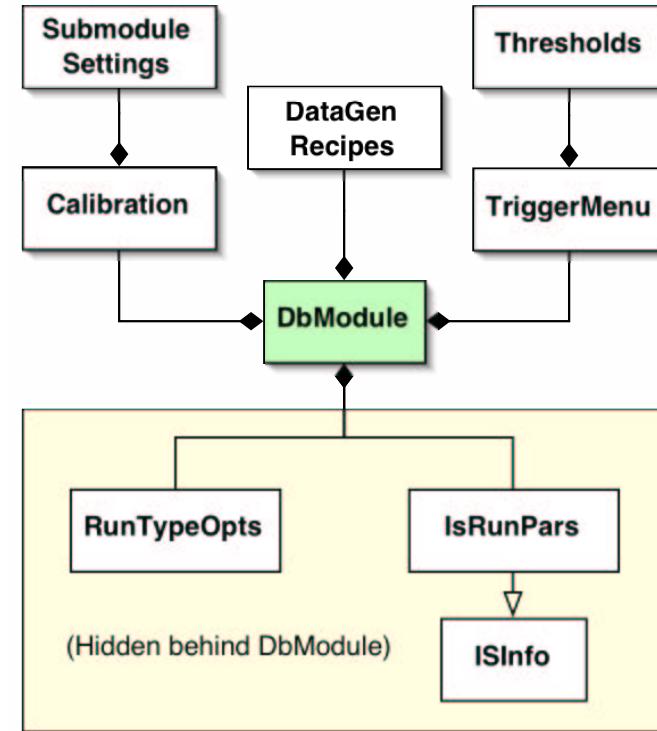
- Partition now contains list of available run type objects (NB different from Online list of run type strings)
- Also now contains list of default DataGenRecipes (NB must now be linked explicitly to be found)
- Links to lists of calibration and trigger menu files as before
- Plus all the stuff inherited from the parent Partition class



# Database Developments (4)

## L1CaloPartition

- DbModule returns XxxCalibration objects as before (for modules with calibration data) and a pointer to the trigger menu
- New RunTypeOptions objects remain hidden (values returned via DbModule subclass APIs – as with the IS run parameters)
- DataGenRecipes are returned as before, but selecting new run type may change which ones are used (ie dont cache DataGenRecipes)



# Run Control and Module Services (1)

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## What happens at Boot, Load

- RC Boot: basic initialisation of run controller
- RC Load:
  - initialise HDMC, open database
  - create CtrlModule for each module: read its parts file and find its DaqModule  
(NB some modules, eg DSS, make VME accesses at this point)
  - DaqModule::initModule – basic initialisation (no DB)
  - DaqModule::setDbModule – pass DbModule
  - DaqModule::setModuleStatusPointer – pass L1CaloModuleStatus object
  - DaqModule::disable() – inhibit input/output
  - DaqModule::load() – perform load actions (finally)  
*(assumed to be only reset, firmware check and clock setting)*

# Run Control and Module Services (2)

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## What happens at Configure, Start

- RC Configure:
  - RC (re)reads IS parameters, (re)sets run type
  - DaqModule::configure() – perform configure actions  
*(download most settings: calibration, trigger menu, test vectors)*
- RC Start:
  - RC (re)reads IS parameters, (re)sets run type
  - If calibration, initialise calibration parameter sequence
  - DaqModule::start() – perform start actions  
*(reload calibration parameter being scanned?)*
  - DaqModule::enable() – inhibit input/output
  - DaqModule::updateStatus() – get status and save to IS
  - RC starts any required processes

# Run Control and Module Services (3)

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## What happens at Pause, Resume

- RC Pause:
  - RC (re)reads IS parameters
  - DaqModule::disable() – inhibit input/output
  - DaqModule::pause() – perform pause actions  
*(reload calibration parameter being scanned?)*
  - DaqModule::updateStatus() – get status and save to IS
- RC Resume:
  - RC (re)reads IS parameters
  - DaqModule::resume() – perform resume actions
  - DaqModule::enable() – inhibit input/output
  - DaqModule::updateStatus() – get status and save to IS

# Run Control and Module Services (4)

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## What happens at Stop, Unconfigure, Unload, Idle

- RC Stop:
  - RC (re)reads IS parameters, (re)sets run type
  - RC stops any processes it started
  - DaqModule::disable() – inhibit input/output
  - DaqModule::stop() – perform stop actions
  - DaqModule::updateStatus() – get status and save to IS
- RC Unconfigure:
  - DaqModule::deconfigure() – perform unconfigure actions (if any)
- RC Unload:
  - DaqModule::unload() – perform unload actions (if any)
- RC Idle: (called automatically every few seconds)
  - DaqModule::updateStatus() – get status and save to IS (if running)