

# Scientific Measurement

PHY-103

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Lecture 4 - Error Propagation



## Measurement Uncertainty



Imagine you need to determine area of a table

You measure  $x$  and  $y$  the sides of the table

$$x = 95.0 \pm 0.5 \text{ cm}$$

$$y = 190.0 \pm 0.5 \text{ cm}$$

$$\text{Area} = 1.81 \text{ m}^2$$

What is the uncertainty on the area?

Any quantity determined from measurements will also have an uncertainty!



Consider  $i$  measurements of area  $A$   
 Uncertainty of  $A$  is given by std deviation of all  $i$  measurements

$$A = x \times y$$

$$A_i = \bar{A} + \Delta A_i = (\bar{x} + \Delta x_i)(\bar{y} + \Delta y_i)$$

$$= \bar{x}\bar{y} + \bar{x}\Delta y_i + \bar{y}\Delta x_i + \Delta x_i\Delta y_i$$

$$\bar{A} = \bar{x}\bar{y}$$

$$\Delta A_i = \bar{x}\Delta y_i + \bar{y}\Delta x_i + \Delta x_i\Delta y_i$$

ignore terms like  $\Delta x\Delta y$  if  $x$  and  $y$  are independent  
 this is the covariance term  
 is correlation of errors in  $x$  and  $y$   
 = 0 if  $x, y$  are random & indep.

$$\sigma_A^2 = \frac{1}{N-1} \sum_i (\Delta A_i)^2$$

$$= \frac{1}{N-1} \sum_i (\bar{x}\Delta y_i + \bar{y}\Delta x_i)^2$$

$$= \frac{1}{N-1} \sum_i (\bar{x}^2\Delta y_i^2 + \bar{y}^2\Delta x_i^2 + 2\bar{x}\bar{y}\Delta x_i\Delta y_i)$$

$$\sigma_A^2 = \bar{x}^2\sigma_y^2 + \bar{y}^2\sigma_x^2$$

$$\left(\frac{\sigma_A}{A}\right)^2 = \left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2$$



For  $F = \text{function}(x, y)$  then

$$\sigma_F^2 = \left(\frac{\partial F}{\partial x}\right)^2 \sigma_x^2 + \left(\frac{\partial F}{\partial y}\right)^2 \sigma_y^2$$

provided that  $x$  and  $y$  are independent measurements

This is the last formula you will need in this course - memorise it!

Consider the table area example:

Area =  $x \cdot y$

$$\sigma_A^2 = \left(\frac{\partial A}{\partial x}\right)^2 \sigma_x^2 + \left(\frac{\partial A}{\partial y}\right)^2 \sigma_y^2$$

$$= y^2 \sigma_x^2 + x^2 \sigma_y^2$$

$$\left(\frac{\sigma_A}{A}\right)^2 = \left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2$$

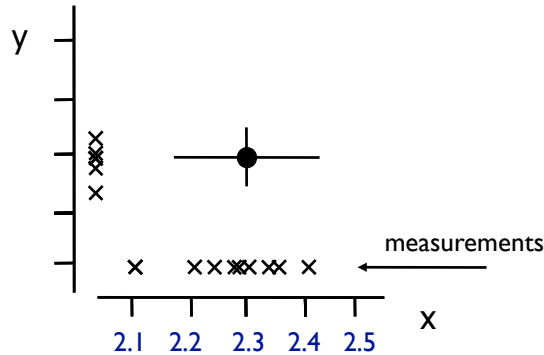
Fractional error on  $A$  is quadratic sum of fractional errors on  $x$  &  $y$

Pythagoras' Theorem is an example of a quadratic sum:  $a^2 = b^2 + c^2$



### Why a quadratic sum?

Combined error can never be smaller than on measured quantities



$x = 95.0 \pm 0.5$  cm means:

High probability true value lies between  $x - \Delta x$  and  $x + \Delta x$

Note: you do not guarantee that this is true

(we will quantify this probabilistic statement later)

If errors are random and  $x, y$  measured independently then equally probable to measure underestimate OR overestimate in  $y$

Probability to measure overestimate in  $x$  AND  $y$  simultaneously is small  
Independent measurements = subject to only random uncertainties



Lets look at pendulum example...

$$T = 2\pi\sqrt{\frac{L}{g}} \qquad g = 4\pi^2 \frac{L}{T^2}$$

$$\sigma_g^2 = \left(\frac{\partial g}{\partial L}\right)^2 \sigma_L^2 + \left(\frac{\partial g}{\partial T}\right)^2 \sigma_T^2$$

$$\sigma_g^2 = \left(\frac{4\pi^2}{T^2}\right)^2 \sigma_L^2 + \left(\frac{-8\pi^2 L}{T^3}\right)^2 \sigma_T^2$$

$$\left(\frac{\sigma_g}{g}\right)^2 = \frac{\sigma_L^2}{L^2} + 4\frac{\sigma_T^2}{T^2}$$

$$\frac{\sigma_g}{g} = \sqrt{\frac{\sigma_L^2}{L^2} + 4\frac{\sigma_T^2}{T^2}}$$



Consider several simple examples -  $F$  is a function of variables  $x, y, z, \dots$  and  $k$  is a constant

$$F = x + k \quad \sigma_F = \sigma_x \quad \text{absolute error remains the same}$$

$$F = xy \quad \left(\frac{\sigma_F}{F}\right)^2 = \left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2 \quad \text{fractional errors add in quadrature}$$

$$F = kx \quad \frac{\sigma_F}{F} = \frac{\sigma_x}{x} \quad \text{fractional error remains unchanged}$$

$$F = x^n \quad \left(\frac{\sigma_F}{F}\right)^2 = n^2 \left(\frac{\sigma_x}{x}\right)^2 \quad \text{fractional error is scaled by } n$$

All these results derived from general formula

Results always given in terms of absolute / fractional error on measured quantity

Total error is never smaller than measurement error!



How about sums and differences?

$$F = x + y \quad \sigma_F^2 = \sigma_x^2 + \sigma_y^2 \quad \text{absolute errors add in quadrature}$$

$$F = x - y \quad \sigma_F^2 = \sigma_x^2 + \sigma_y^2 \quad \text{absolute errors add in quadrature}$$

In both cases error is the same, but  $F$  can be very different!

Consider  $F=x+y$       $x = 10 \pm 1$       $y = 9 \pm 2$

$$F = 19 \pm \sqrt{(1^2+2^2)}$$

$$F = 19 \pm \sqrt{5}$$

$$F = 19 \pm 2 \quad \text{number of sig. figs not } \pm 2.23 \quad !$$

Consider  $F=x-y$

$$F = 1 \pm \sqrt{(1^2+2^2)}$$

$$F = 1 \pm \sqrt{5}$$

$$F = 1 \pm 2 \quad \text{error is larger than the central value!}$$



Formula can be trivially extended to many independent variables,  $x, y, z, \dots$

$$\sigma_F^2 = \left(\frac{\partial F}{\partial x}\right)^2 \sigma_x^2 + \left(\frac{\partial F}{\partial y}\right)^2 \sigma_y^2 + \left(\frac{\partial F}{\partial z}\right)^2 \sigma_z^2 \dots$$

Note: Largest error contribution comes from largest error source

Can sometimes neglect one error if it is much smaller than others

$$\frac{\sigma_g}{g} = \sqrt{\frac{\sigma_L^2}{L^2} + 4\frac{\sigma_T^2}{T^2}}$$

If  $\frac{\sigma_L}{L} = 1\%$  and  $\frac{\sigma_T}{T} = 5\%$

then we can neglect error on  $L$

By inspection we see  $\frac{\sigma_g}{g} = 2\frac{\sigma_T}{T}$



Full example involving products, sums, powers & multiplicative factors!

Newton's equations for distance travelled by object

$$s = vt + \frac{1}{2}at^2$$

velocity  $v = 200 \pm 10$  m/s  
 acceleration  $a = 12 \pm 2$  m/s<sup>2</sup>  
 time  $t = 6.0 \pm 0.2$  s

$$s = 1416 \text{ m}$$

$$\sigma_s^2 = \left(\frac{ds}{dv}\right)^2 \sigma_v^2 + \left(\frac{ds}{dt}\right)^2 \sigma_t^2 + \left(\frac{ds}{da}\right)^2 \sigma_a^2$$

$$\frac{ds}{dv} = t \quad \frac{ds}{dt} = v + at \quad \frac{ds}{da} = \frac{1}{2}t^2$$

$$\sigma_s^2 = (t)^2 \sigma_v^2 + (v + at)^2 \sigma_t^2 + \left(\frac{1}{2}t^2\right)^2 \sigma_a^2$$

$$\sigma_s^2 = 6^2 \times 10^2 + (200 + 12 \times 6)^2 \times 0.2^2 + \left(\frac{1}{2} \times 6^2\right)^2 \times 2^2$$

$$\sigma_s = \sqrt{3600 + 2959 + 1296}$$

$$\sigma_s = 88.6$$

$$s = 1416 \pm 89 \text{ m}$$



Beware: some complex formulae can lead to long calculations

May not be worthwhile - use your judgement

In such cases use:

$$\sigma_F \approx \frac{1}{2} |F(x - \sigma_x) - F(x + \sigma_x)|$$

$$\sigma_F^2 \approx \left( \frac{|F(x - \sigma_x, y) - F(x + \sigma_x, y)|}{2} \right)^2 + \left( \frac{|F(x, y - \sigma_y) - F(x, y + \sigma_y)|}{2} \right)^2$$

In other words calculate the value of  $F$  for  $x + \sigma_x$  and for  $x - \sigma_x$  and take half the difference